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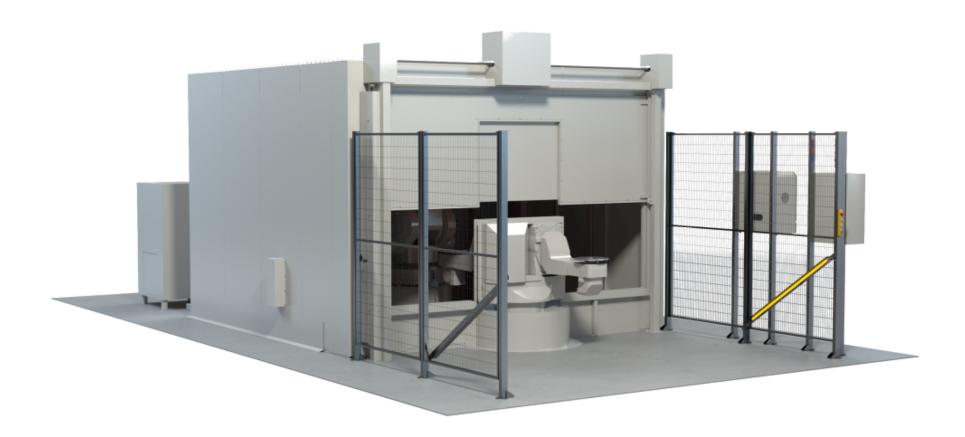
PERMAFLEX is our standardised laser robot cell that embodies 30 years of laser experience and more than 200 deliveries of customised robot cells. In simple terms, we've packed all our knowledge into a single robot cell, for our customers like you to benefit from.



PERMAFLEX is equipped with tools for both welding and cutting. In the cutting version, the laser beam is transmitted by way of high-power fibre from the laser to a robot-mounted cutting tool. In the welding version, the beam is transmitted to a welding tool with a joint locator and optional joint tracking. Standardisation makes the manufacture of the PERMAFLEX cell cost-effective, shortens delivery times, and speeds up commissioning. Overall this results in great economy for our customers, and that's before we even look at the unique features and performance of PERMAFLEX. PERMAFLEX Weld has an in-built joint identification feature which reduces stoppage time when starting a laser welding job and ensures a safer welding process. The optional joint tracking further improves performance and allows for more complex welding geometries to be catered for. With PERMAFLEX, shaped or deep-drawn sheet metal can be welded or cut with high levels of efficiency. The latest in laser technology and robotics is combined with in-depth knowledge of laser processes and system technology.



PERMAFLEX allows you to build on the base cell by way of a variety of handling solutions and laser sizes, making it possible to adapt the cell to a variety of different applications.



The highlight of our laser welding cell is the joint identification and tracking feature, which we have refined in our deliveries to customers including Westinghouse, Volvo Cars, and Volvo Aero. The features are available by way of the laser process tools that the robot positions during the laser welding process. In simple terms, even the "blindest" and "shakiest" of robots can, with a wide reach, get a good view of their welding path, precision, and fine motor skills even at high welding speeds. The robot finds the weld joint in a three-dimensional world and correctly positions the laser weld.

			WELDING		CUTTING		ATTACHMENT	
LAGED	MODEL		WELDING		CUTTING		ATTACHMENT	
LASER	MODEL		Fiber/disc	Fiber/disc	Fiber/disc	Fiber/disc	Fiber/disc	Direct-diode
	AVERAGE POWE	R (W)	2000	4000	6000	1000	3000	4000
Welding data, typical [m/min] (shield gas) *	Low alloy steel	1mm	4	12.5	15-20			
	(Ar)	3mm	1.5	5	7			
	Stainless steel	1mm	4	12.5	15-20			
	(Ar)	3mm	1.5	5	7			
	Aluminium	1mm	4	16.5	-			
	(Ar)	3mm	1	6.5	-			
Cutting data,	Low alloy steel	1mm	-	-	-	8	30	
typical [m/min] (shielding gas)*	(O ₂)	3mm				3	8	
	Stainless steel	1mm	2	2	-	3	35	
	(N ₂)					1	7	
	Aluminium	3mm	-	12/1	-	2	20	
	(N ₂)				0.5	3		
Cladding data, example: 1	Low alloy steel base							
pass width x depth 10x1.25	Stellite 6-coat							
mm Stellite 6 on low alloy steel	(Ar)							
cladding speed (m/min) resp.								0.45
deposition rate (kg/tim).*								2.7
Robot/control system			ABB IRB 4400-45 / IRC 5					
Offline program (option)			RobotStudio					
Beam transfer			Fibreoptic					
Optic configuration			Welding, Cutting					
Safety of laser products class (EN ISO 60825-1:2007)			Class 1					
Laser shield			Double plates with active beam monitoring between the plates					
Doors			Manual sliding doors at the front, opening 1800x2500mm Automatic sliding doors at the front (option)					
Inspection windows				200x100mm				
Indexing table Diameter 2000mm				2 positions				

OPTIONS

Rotating table 1- or 2-axis

Clamp unit/fixture for welding or cutting

DIMENSIONS	LxWxH mm	WEIGHT		
Cell	3800x3800x2900			
Robot		1100 kg		
Control box	970x725x710	150 kg		
Junction box	1000x400x1600	150 kg		
Laser	1600x930x1550	600 kg		

Robot

The robot is a very important component, especially in cutting applications. The choice of robot affects the track accuracy, repeatability, system design, and flexibility of the programming system.

Robot cabling

The location of the cabling is important in terms of both safe operation and quick maintenance. Permanova uses tried-and-tested cabling solutions. The laser system includes I/O signal cabling, optical fibre, and gas pipes on the robot.

1/0

The standard I/O configuration is based on Profinet.

Software

Basic features are included for managing the system and start-up and for carrying out the process (cutting, welding, etc.).

Positioner

To enable rapid switching times and/or repositioning of the component during the cycle, different types of positioners can be integrated into the process enclosure.

Laser

The laser must be set at the correct power level and beam quality for the process in question, be easy to control, and be a reliable beam source. Permanova works with all major laser manufacturers in the market.

Laser cooler

An external heat exchanger or cooling unit can be installed for the laser.

Process tool

The process tool is one of the most important parts of the system. The tool must support the process well and the structure must accommodate the movements of the robot in relation to the geometry of the workpiece.



(optionally process gases, it also reactives electrically controlled pressure regulators for compressed all for various accessiones, sacrius rixing acvices.

Process monitoring

There are different types of process monitoring systems available for welding processes that can be integrated into the system.

Component position sensors

Position sensors can be used to measure and fine-tune the robot's coordinate system for each cycle.

FPS – focus positioning system

An FPS can be integrated into the laser system in order to set up and monitor the actual focus position and cutting nozzle position over time, as well as ensure a stable automated process.

Scrap collection

Various scrap management systems are available for laser cutting systems that produce larger pieces of scrap.

Fixing device

Various fixing devices can be used in the system. The fixing devices can be part of the delivery or be developed separately by an application developer for subsequent integration into the system in collaboration with Permanova. (Not standard.)

Process screen

Electrical safety system

All gates and doors are interlocked and emergency stop buttons are monitored by a safety system. If the safety system is activated, all movements are stopped and the laser beam is turned off.

Laser safety housing

Based on a steel frame with multi-layer wall sections in sheet metal. Different sections can be reinforced in accordance with risk analyses.

Doors

Doors for loading components are included. Their size varies from small hatches to large sliding doors, depending on the size of the component. A manually opened service door is integrated into the laser security housing to allow easy service access to the cell.

Table

For smaller components, a fixed table can be supplied with the system. Fixing devices are mounted to the table.

Monitoring camera kit

An IP camera linked to the station computer/monitor is used in order to view the inside of the cell.

Smoke extractor

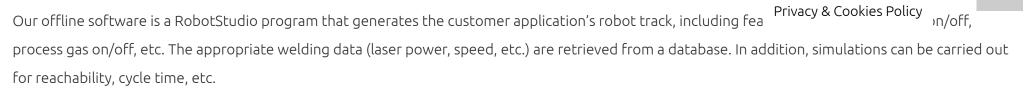
Normally, an opening for a smoke extractor in the cell roof is sufficient for ventilation. For large quantities of smoke, such as in the case of thicker materials, additional smoke extractors can be installed to protect the cell and filter the extracted air. Alloys containing toxic substances must be handled with special care!

Laser enclosure

Laser housing

The laser source can be located in its own secure housing to enable quick and safe access for servicing.

Offline software



HMI (Human Man Interface)

The HMI for the Permaflex concept primarily shows the product selection, station error messages, and safety status.

Training

We provide training in the operation and servicing of our equipment and software, process training, and safety training.

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