## CHEETAH

## C4080 CMOS 12 MP Camera Link ${ }^{\circ}$

## Imperx: C4080

## RUGGEDIZED CAMERA SERIES

The C4080 incorporates the On Semiconductor KAC-12040 CMOS image sensor with a native resolution of $4000 \times 3000$ in a $4 / 3$ " optical format delivering up to 67 frames per second in either global or rolling shutter mode with a Camera Link ${ }^{\circledR}$ or PoCL Full output. Extended dynamic range technology coupled with extremely robust blooming suppression provide clean imagery in even the most severe uncontrolled lighting applications. Cheetah cameras incorporate "smart" wide dynamic range technology which monitors each pixel's exposure and sets the exposure to one of four user selectable values based on the intensity of the source at the pixel. CMOS technology eliminates smear columns from areas of ultra-bright intensity and specular reflections in uncontrolled lighting applications.

## Specifications

| Feature | Description | Feature | Description |
| :---: | :---: | :---: | :---: |
| Interfaces available | Camera Link ${ }^{\circledR}$ Base, Full/Deca (CLF) w/PoCL | Strobe Output | 2 strobes, programmable position and duration |
| Resolution | $4000 \times 3000$ | Pulse Generator | Yes, programmable |
| Sensor | KAC-12040, CMOS Color/Mono | Image Enhancement | Vertical/Horizontal flip |
| Sensor Format | $18.8 \mathrm{~mm}(\mathrm{H}) \times 14.1 \mathrm{~mm}(\mathrm{~V}) 23.5 \mathrm{~mm}$ diagonal $4 / 3^{\prime \prime}$ optical format | Data Corrections | Defective/hot pixel correction (static, dynamic) |
|  |  | Lens Mount | F-Mount (Default), C, M42, EF Canon |
| Pixel Size | $4.7 \mu \mathrm{~m}$ | Supply Voltage Range | 12VDC (5V - 30V), 1.5 A inrush |
| NIR Sensitivity | 850nm: 15\%, 950nm: 5\% | Camera Current | Typical: 0.30A, Maximum: 0.33A |
| Shutter | Global shutter (GS), rolling shutter (RS) | PoCL | PoCL capable in base/medium/full mode |
| Digitization | 10 or 12 bit | Size - Width/Height/Length | $72.0 \mathrm{~mm}(\mathrm{~W}) \times 72.0 \mathrm{~mm}(\mathrm{H}) \times 34.3 \mathrm{~mm}$ (L) - |
| Frame Rate | 27 fps (12 bit), 55 fps (10 bit), 67 fps ( 8 bit) |  | Applies to all interfaces |
| Camera Link Clock Rate | 85 MHz | Weight | 385 g |
| Dynamic Range | 73 dB (RS), 56 dB (GS) | Vibration, Shock | TBD |
| Bit Depth | 8, 10, 12 bit | Environmental | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ Operating, $-50^{\circ} \mathrm{C}$ to $+90^{\circ} \mathrm{C}$ |
| Analog Gain Control | 12-bit: 0-12 dB (16 steps); 8 or 10-bit: 0-18 dB (32 steps) | Humidity | Storage <br> 10\% to 90\% non-condensing |
| Digital Gain | 24 dB (128 steps) | MTBF | > 323,000 hours @ $40^{\circ} \mathrm{C}$ (Telcordia SR-332 |
| White Balance | Manual, auto, off |  | Method 1) |
| Shutter Speed | $1 \mu \mathrm{~s} / \mathrm{step}, 5 \mu \mathrm{~s}$ to $1.0 \mathrm{sec}(\mathrm{GS}), 2 \mu \mathrm{~s}$ to 1.0 sec (RS) | Military Standard | MIL-STD-810F |
|  |  | Regulatory | FCC Part 15 Class A, CE, RoH |
| Exposure Control | Off, internal, external |  |  |
| Regions of Interest (ROI) | 1 ROI |  |  |
| Averaging Decimation | 4:1, 9:1 (both color and monochrome) |  |  |
| Sub-sampling Decimation | $N$ pixels: 2, 4, 6.30 by every $M$ pixels: 2,4 , 6... 32 |  |  |
| Trigger Inputs | External, pulse generator, software, computer |  |  |
| Trigger Options | Edge, debounce |  |  |
| Trigger Modes | Internal, External, Computer |  |  |
| Wide Dynamic Range | 100 dB (typ) GS, up to 3 knee points, piecewise linear |  |  |
| External Inputs/Ouputs | 2 IN (OPTO, LVTTL) / 2 OUT (OPTO, TTL) |  |  |

## Imperx: C4080 Applications

The C4080 incorporates a number of unique features tailored to reduce system complexity, maximize interface bandwidth, and expand the usable operational range.
Aerospace • Satellites • Surveillance • Military and Non-Military Ground Vehicles • Ball Grid Array • Printed Circuit Board Inspection - Motion Analysis •Broadcast Television • Telepresence • Unmanned Aerial Vehicles • Machine Vision • Reconnaissance • Aerospace • Intelligent Traffic Systems • Aerial Imaging • Open Road Tolling Systems • Situational Awareness

## Absolute Quantum Efficiency



## Dimensions



## BACK




Software/Drivers/Interface


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